Modeling & Simulation in Automotive Industry

Prediction of Energy Consumption in Electric Vehicles

Oleg Gusikhin Ford Research & Advanced Engineering Dearborn, Michigan, USA



- Introduction
- Selected Simulation Applications at Ford
 - Virtual Manufacturing & e-Workcell
 - Virtual Test Track Experiment (VIRTTEX)
- Predication of BEV Energy Consumption
 - BEV Introduction Challenges
 - Vehicle Systems Modeling
 - Traffic Simulation Integration
 - Simulation Results
- Conclusion



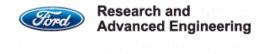
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Ford Motor Company



- Global automotive industry leader based in Dearborn, MI.
- Manufactures and distributes automobiles in 200 markets across six continents.



Ford Brands



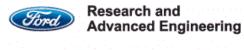












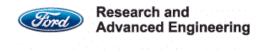
Communication & Infotainment Technology

Ford SYNC

MyFord Touch







Ford Hybrid and Electrical Vehicles





FOCUS Electric

Coming Late 2011







Ford Research & Advanced Engineering





Vehicle & Enterprise Sciences Research Lab

□ Information Sciences & Connectivity



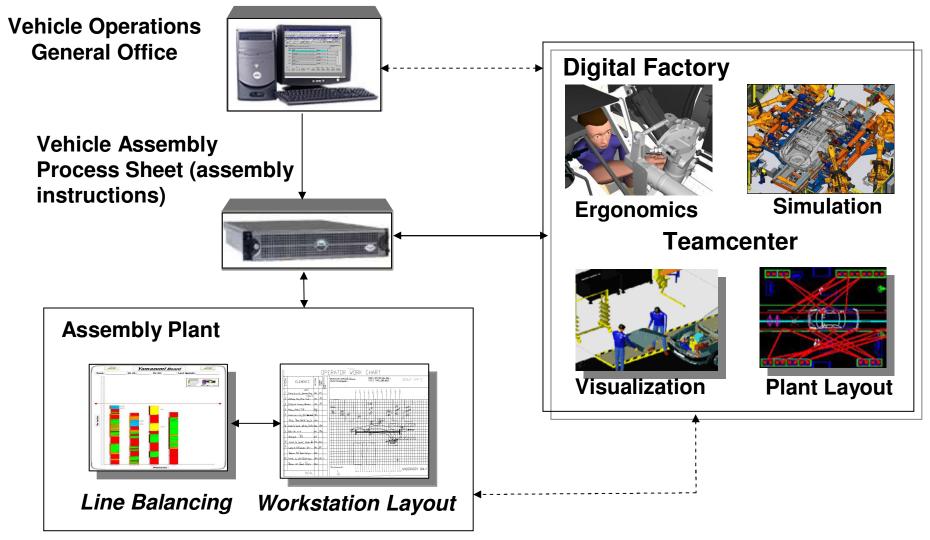
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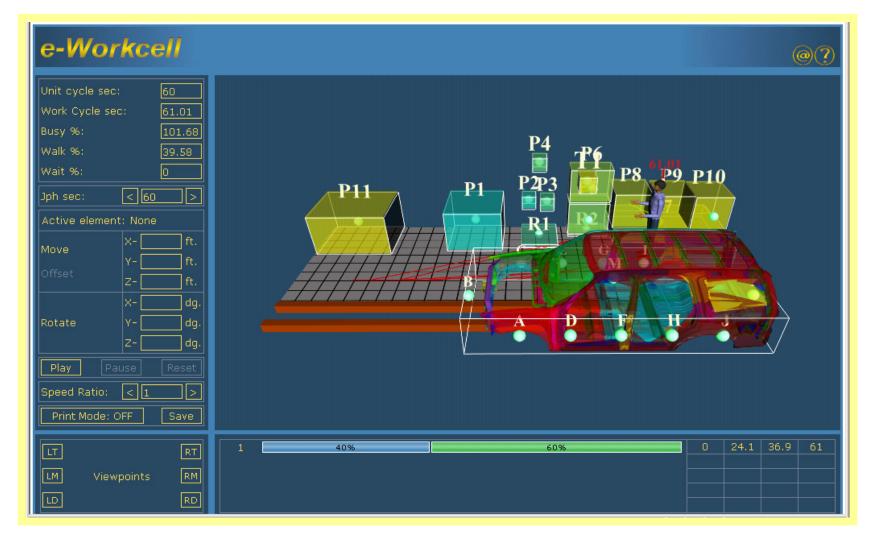


Vehicle Assembly Planning





e-WorkCell





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Virtual Test Track Experiment (VIRTTEX)



Displays

- 180° forward
- 120° rear



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	Acceleration	Velocity	Displacement
Longitudinal/ Lateral	> 0.6g	> 1.2m/s	± 1.6m
Vertical	1.0g	1.0m/s	± 1.0 m
Pitch/ Roll	> 200deg/s ²	> 20deg/s	± 20 deg
Yaw	> 200deg/s ²	> 20deg/s	± 40 deg

Inside VIRTTEX

- Realistic sound cues
- Steering feedback





Safety-Related Studies in VIRTTEX

- Types of Studies
 - Warning HMI for LDW, FCW, ACC, ...
 - Distracted driver
 - Drowsy driver
- Primary Study Results: Driver Performance
 - Quantitative/Objective data
 - Brake/steer reaction times to imminent forward collision event
 - Eyes-off-road time for secondary tasks



VIRTTEX





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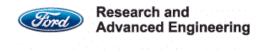


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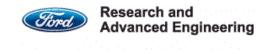
2012 FOCUS BEV





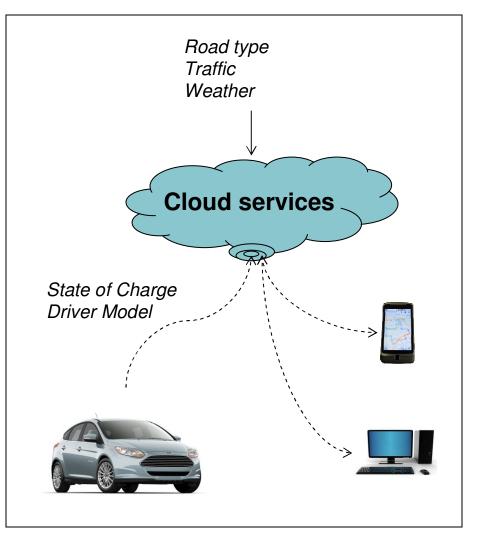
Potential issues with BEV ownership

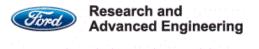
- BEV lack the range of conventional vehicles
- Charging stations are sparse compared to gas stations
- Charging takes a long time compared to a fill up



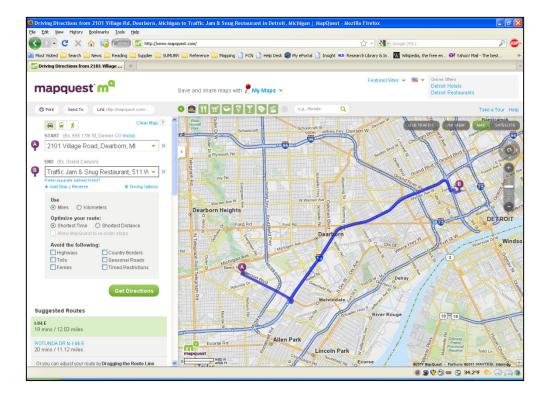
Telematics and cloud-based services can help BEV owners

- Give the driver a energy efficient route
- Compute and communicate
 the distance to empty
- Help the driver plan trips that consider driving range, locations of charging stations and charging times
- Lots of others

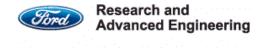




What route will I prefer?

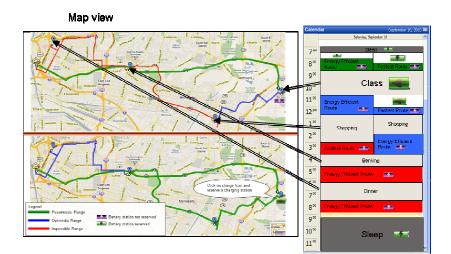


- What is the cheapest route?
- What is the greenest route?
- What is the fastest route?
- What is the shortest route?
- What is the scenic route?
- What is the safest route?



Can I make it through the day?

Desktop Applications:



Mobile Applications:



- How do I get to the places I need to go without killing my battery?
- If I need a battery charge, how can I spend my time while it is charging?
- How shall I organize my day around keeping my vehicle charged?

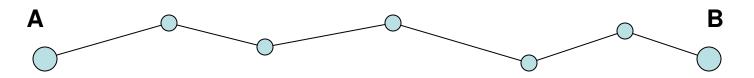




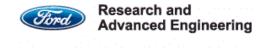
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Problem Statement

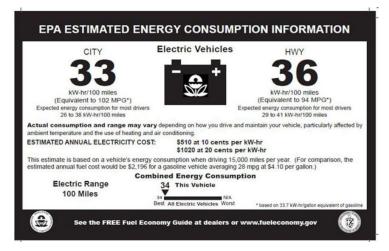
- Accurate energy consumption estimates are at the heart of many new features needed for BEV drivers
- Digital maps represent road system as a graph where arcs correspond to the road segments with the given characteristics (e.g. road type, grade, speed limit, etc.)



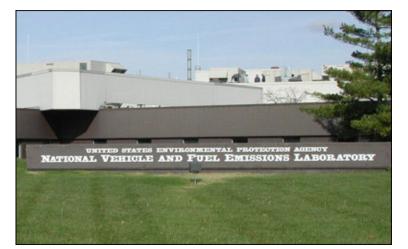
- The energy consumption over the given route is the sum of power consumption estimates for the arcs comprising that route
- We need a method to estimate energy consumption for the given static and dynamic parameters of the road segment

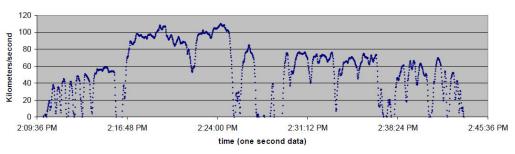


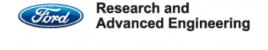
Using the vehicle sticker to determine energy consumption



- MPG (for a BEV kWh/mile) are determined using a standard laboratory test using drive cycles as an input
- Sticker mileage is based on laboratory tests designed to compare energy efficiency of vehicles, but not for in-use energy consumption







Factors that influence energy consumption

- Factors that can be accurately predicted:
 - the road type
 - topography
 - vehicle parameters
- Factors that have a lot of noise:
 - weather
 - traffic control
 - vehicle interactions
 - driver characteristics





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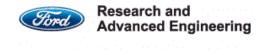


Vehicle Systems Modeling Tools

POWERTRAIN SYSTEMS ANALYSIS TOOLKIT (PSAT)
 Argonne National Laboratory

Vehicle File:		Configuration: par_2wd_p2_au
1. Vehicle 2. Simulation Setup 3. Run Simulations		
1. Drivetrain Configuration 2. Drivetrain Components 3. Contr	and the second second	no canal
Configuration	Configuration List	Description
Convertional	per 2wd p2 eu	2 wheel-drive pre-transmission parallel configuration with automatic transmission
	par 2005 p2 au 2005	2 unes des pre internetes paras configurios ott a Londo travencior and 2 areas atom
Carola Rese Constant Trenge Couping Trenge		

 Ford Simulink-CVSP is Ford's corporate standard tool for vehicle performance and fuel economy modeling and simulation

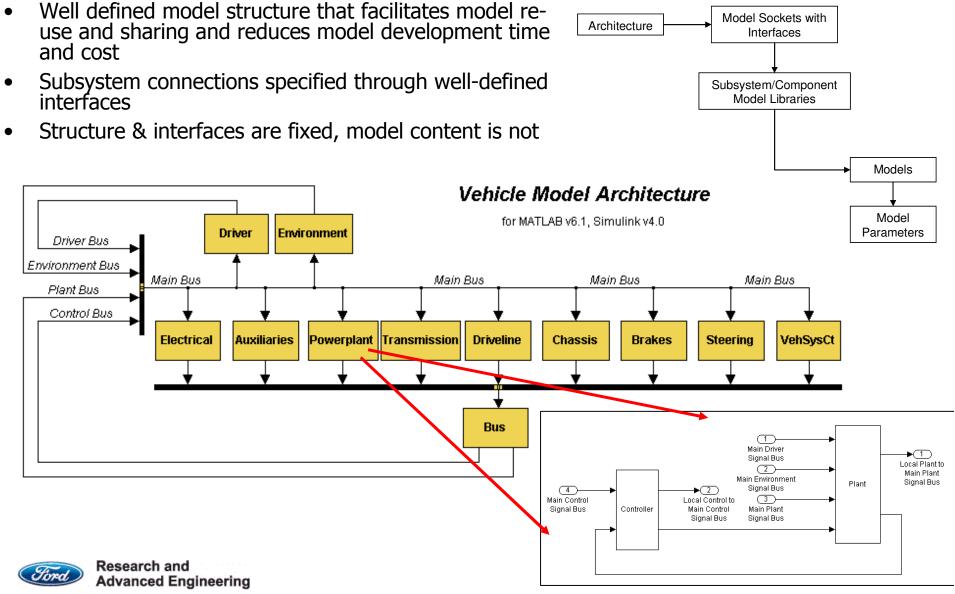


Simulink-CVSP

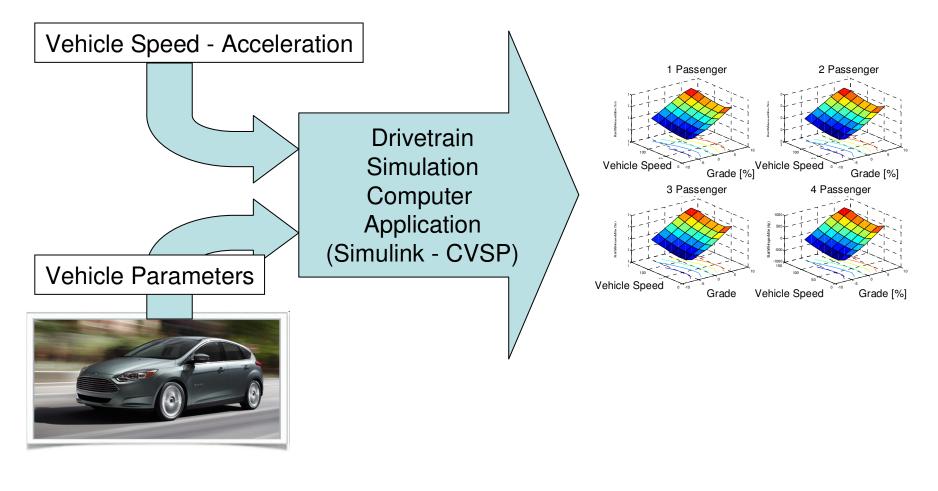
- Used on vehicle programs to set Performance & Fuel Economy targets
- Model architecture and subsystem interfaces follow Vehicle Model Architecture
- Includes extensive set of component models and vehicle / component parameter database
- Supported by company-wide processes to generate vehicle and component parameter data for new programs
- Includes standard test management and report generating scripts
- Capabilities can be extended by users
 - New models can be added to existing libraries (e.g. Hi-fi engine model into engine library)
 - New libraries with new models can be added

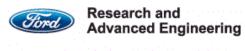


Vehicle Model Architecture



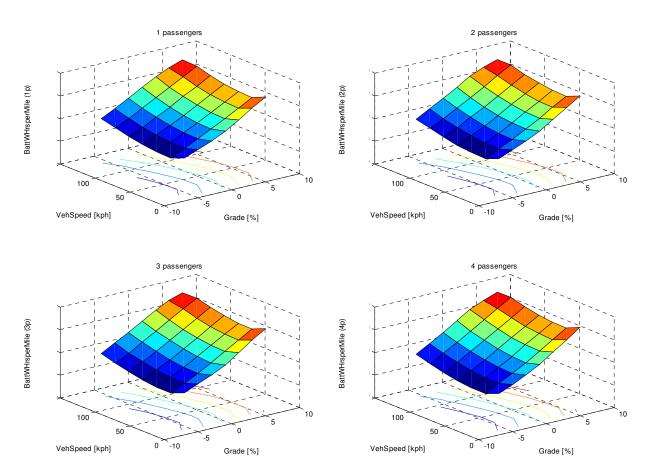
Predicting energy consumption for continuous values

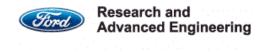




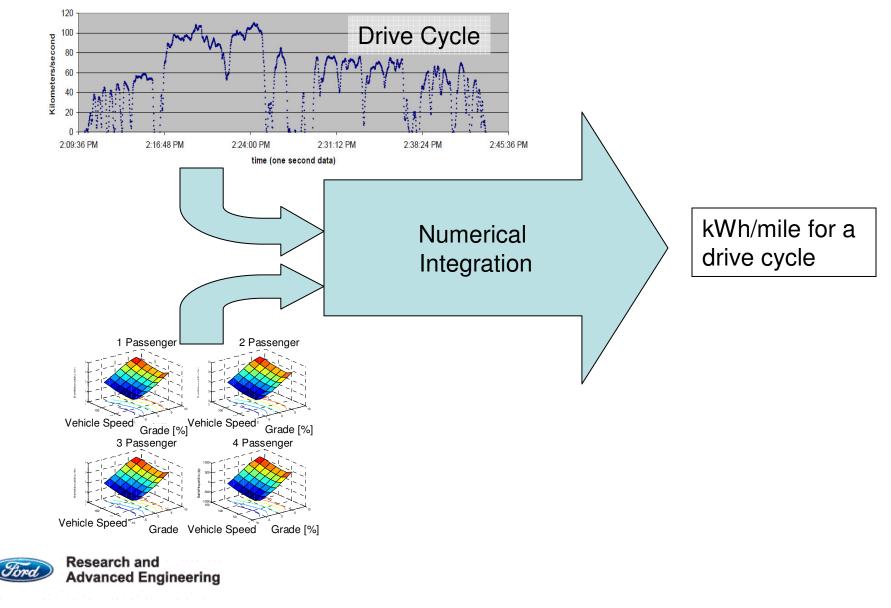
Sample Energy Consumption Maps

Acc Load = 800 [W]

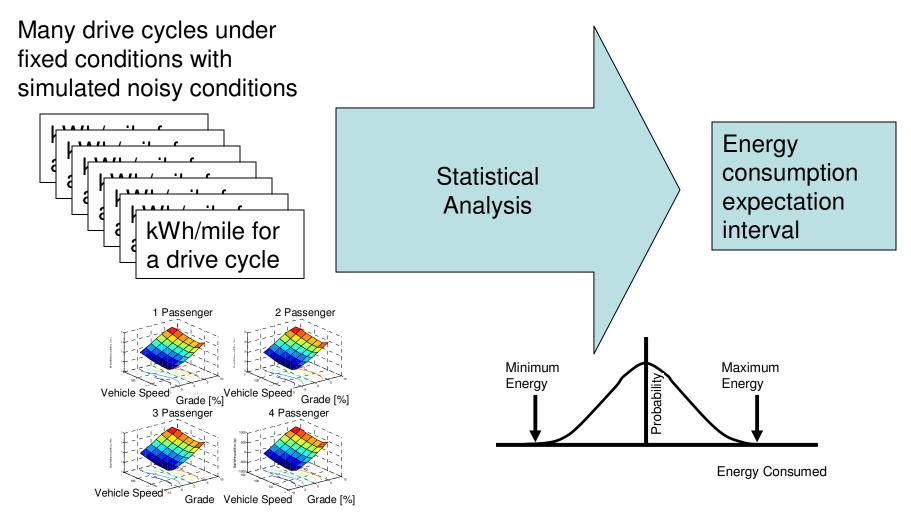




Computing kWh/mile for a drive cycle



Multiple drive cycle energy ranges





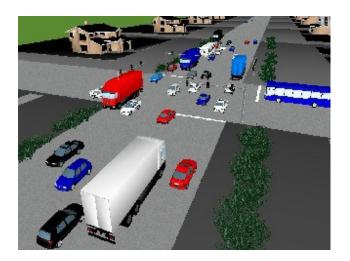
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Traffic Simulation VISSIM

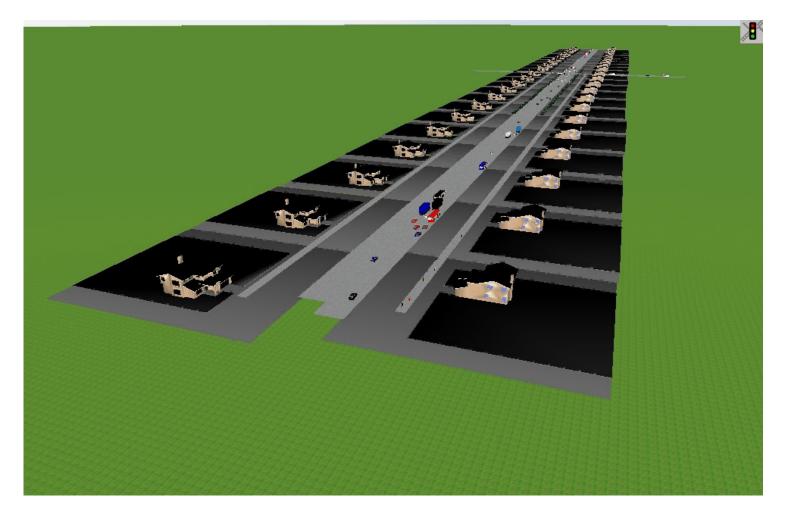
- Transportation system design, analysis and optimization applications:
 - Analysis of urban traffic and public transportation operations
 - Optimization and finetuning of signal priority logic
 - Comparison of transportation design alternatives

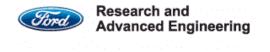




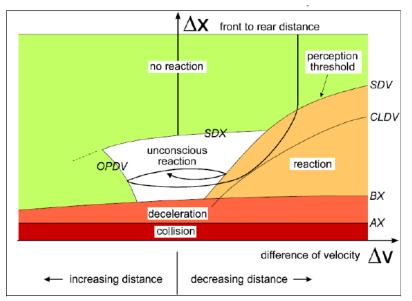


Traffic Simulation Example

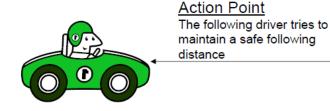




Wiedemann's Psycho-physical model



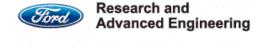
Car following logic (Wiedemann 1974)





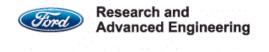
Weber's Law

The variation the driver can perceive is the distance times the Weber fraction (typically 10%)



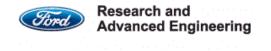
Conservative Driver





Aggressive Driver

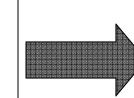




Simulation Framework

Traffic Simulation

Road Model Traffic Conditions Driver Model





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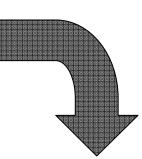
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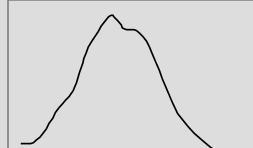
Grace Vehicle Speed Grace [%]

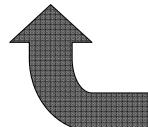
<u> </u> Ārade [%]

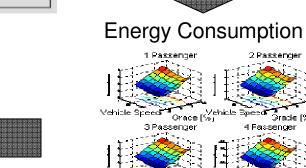
Accessory loads

Vehicle Weight

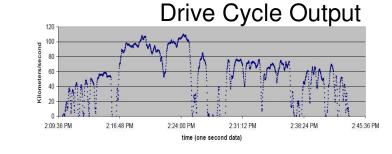


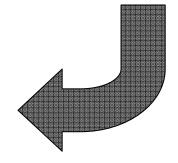






Vehice Speed

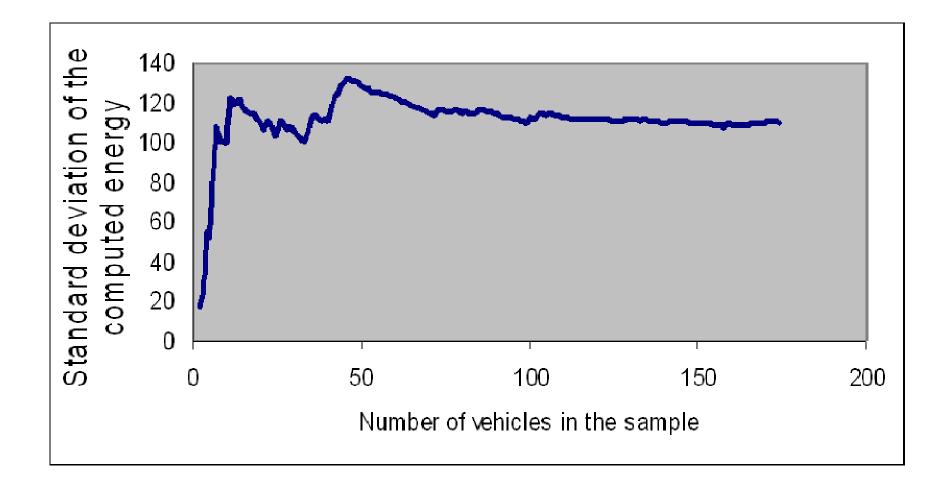


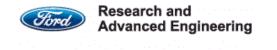




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Standard Deviation vs. Sample Size



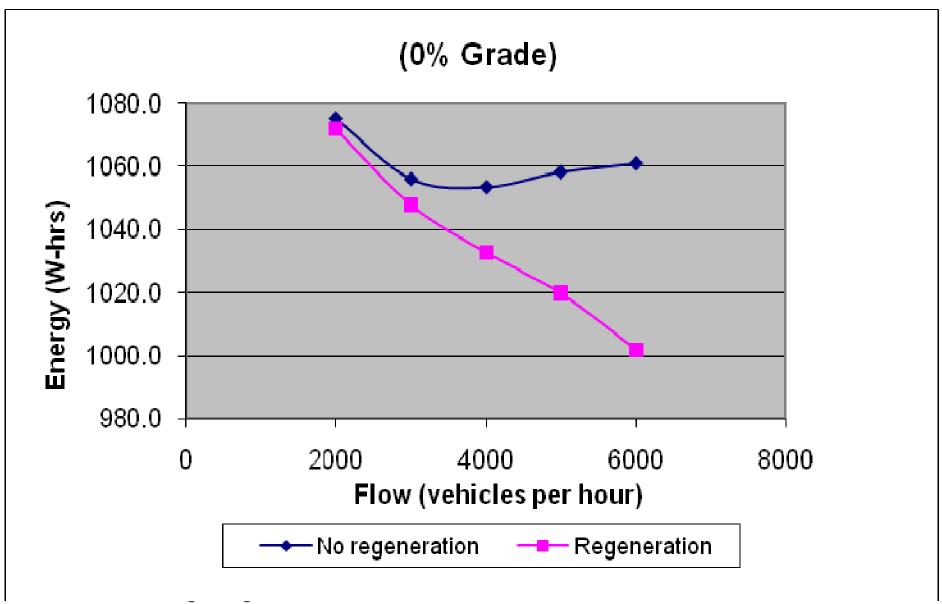


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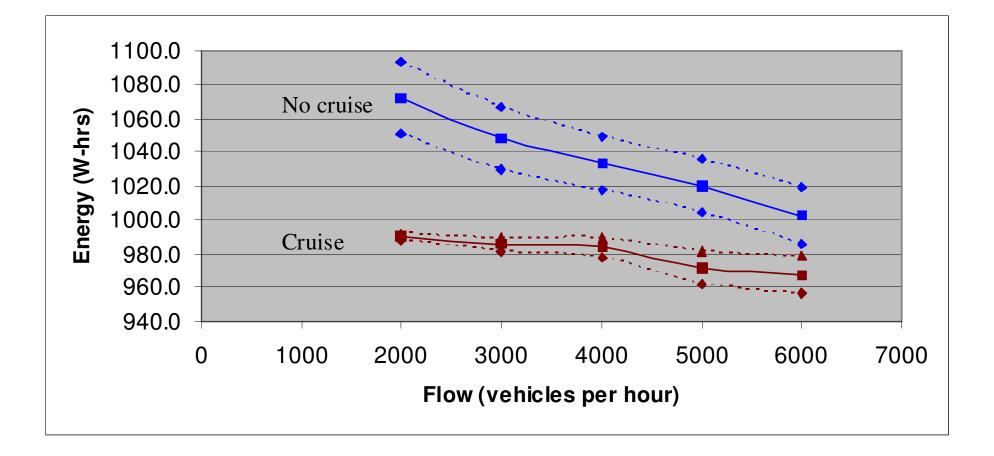


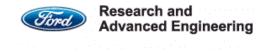
The effect of regeneration



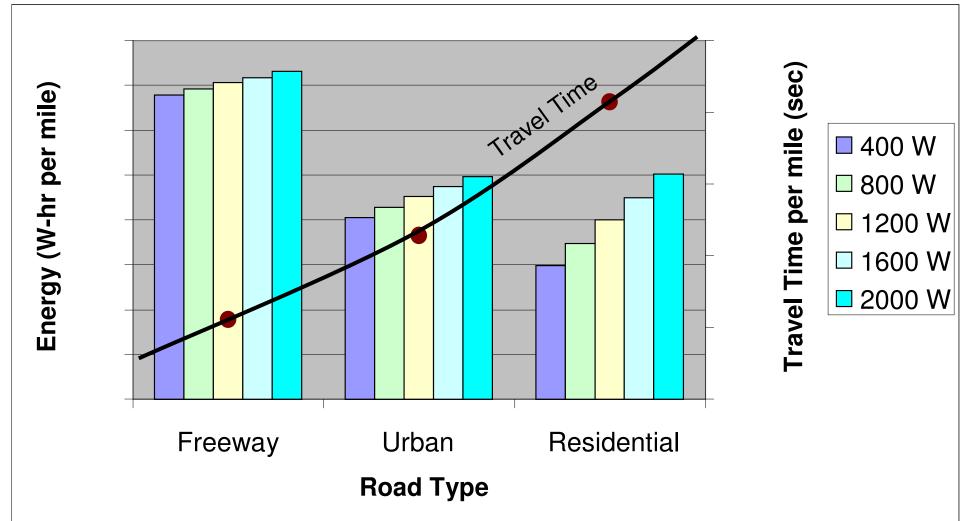
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Effect of Adaptive Cruise Control

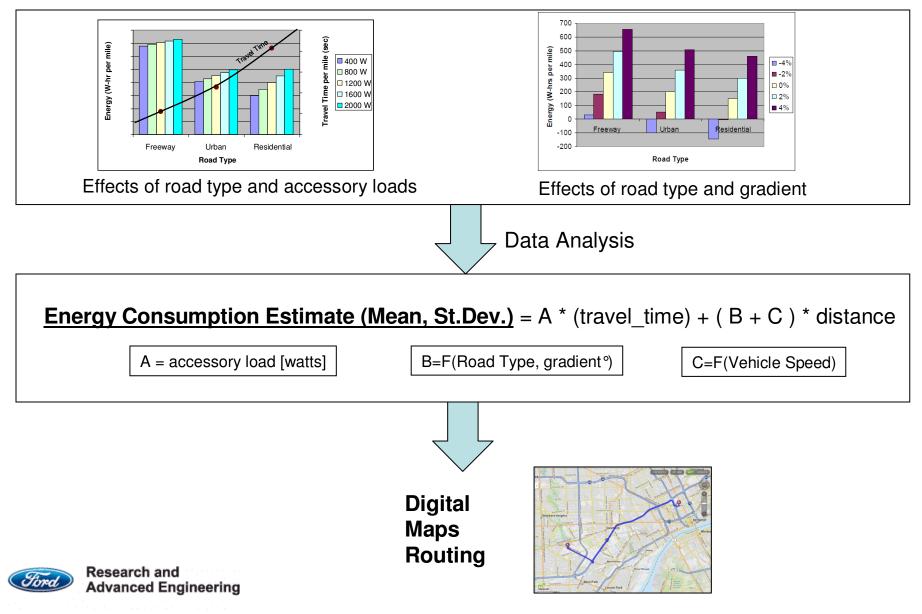




Effects of Road Type, Energy Consumption and Travel Time



Power Consumption Estimates



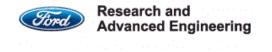
Conclusion

- Integration of Vehicle Systems Modeling and Traffic Simulation
 - enables meaningful energy management features for new vehicles
 - provides an efficient and effective approach for vehicle design optimization and calibration
 - allows to combine road infrastructure design with vehicle design for energy efficient transportation



Acknowledgments

- -Perry MacNeille
- -Mark Jennings
- -Ciro Soto
- -Sujith Rapolu



Q & A



